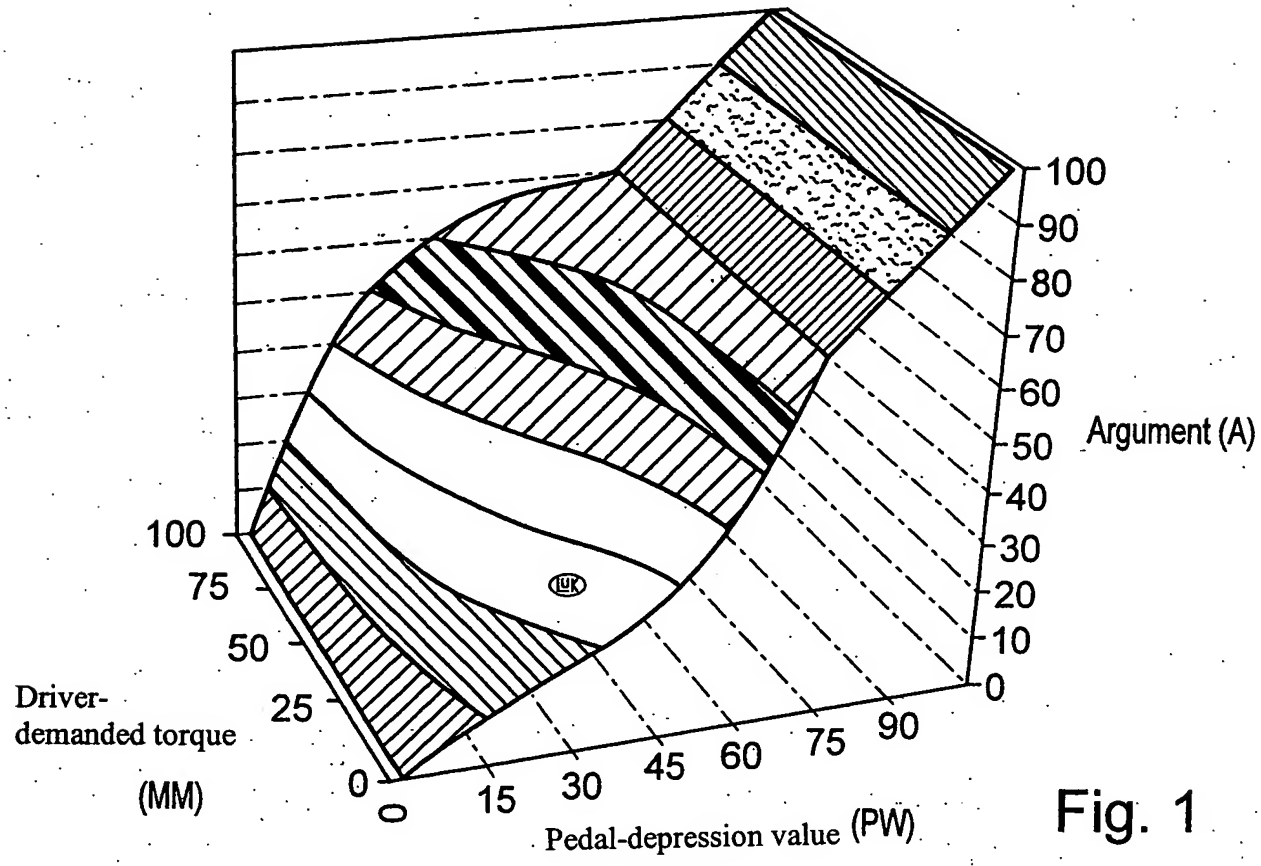
100
90
80
70
60
50
40
30
20
10
0
Argument (A)
100
75
50
25
0
Driver-demanded torque (MM)
0
15
30
45
60
75
90
Pedal-depression value (PW)

Fig. 1